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# Hydromagnetic spectroscopy of the magnetosphere with Pc3 geomagnetic pulsations along the 210° meridian

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**Abstract.** Analysis of Pc3 observational data along the 210° magnetic meridian showed a complicated frequency-latitude structure at middle latitudes. The observed period-latitude distributions vary between events with a “noisy source”: the  $D$  component has a colored-noise spectrum, while the spectrum of  $H$  component exhibits regular peaks that vary with latitude, and events with a “band-limited source”: the spectral power density of the  $D$  component is enhanced at certain frequencies throughout the network. For most ULF events a local gap of the  $H$  component amplitude has been exhibited at both conjugate stations at  $L \simeq 2.1$ . A quantitative interpretation has been given assuming that band-limited MHD emission from an extra-magnetospheric source is distorted by local field line resonances. Resonant frequencies had been singled out with the use of the asymmetry between spectra of  $H$  and  $D$  components. Additionally, a local resonant frequency at  $L \simeq 1.6$  was determined by the quasi-gradient method using the data from nearly conjugate stations. The experimentally determined local resonance frequencies agree satisfactorily with those obtained from a numerical model of the Alfvén resonator with the equatorial plasma density taken by extrapolation of Carpenter-Anderson model. We demonstrate how simple methods of hydromagnetic spectroscopy enable us to monitor simultaneously both the magnitude of the IMF and the magnetospheric plasma density from ULF data.

**Key words.** Magnetospheric physics (Magnetosphere-ionosphere interactions; MHD waves and instabilities; plasmasphere).

## 1 Introduction

A typical feature of the wave structure of the magnetosphere is the large variety of ULF pulsations. The wave structure of a disturbed terrestrial magnetic field may be composed by forced oscillations from external sources, harmonics of resonant Alfvén field line oscillations, cavity-type oscillations of the magnetospheric volume, fluctuations of global current systems, etc. As a result, the most common Pc3–4 pulsations possess complicated spectral forms. The usual application of ULF ground data for the diagnosis of the solar wind (Russell and Fleming, 1976; Yumoto, 1985) and of the magnetosphere (Webb *et al.*, 1977) has relied mainly on the determination of the pulsation frequency. While numerous studies have confirmed that there is strong statistical evidence for the control of Pc3–4 frequency by the magnitude of interplanetary magnetic field (IMF), other studies, including most satellite observations, have not shown such strong control (e.g., see review by Odera, 1986). However, the selection of a proper frequency can be uncertain due to complicated spectral forms of pulsations. Thus the hydromagnetic diagnosis of outer space in fact reduces to a distinct problem, which may be called a hydromagnetic spectroscopy, i.e., to the physical interpretation of spectral peaks of recorded ULF hydromagnetic emissions. Reliable interpretation of ground-based data cannot be done by just analyzing spectral features of some wave components only. The physical nature of particular spectral peaks can be revealed with the use of additional information about spatial or polarization structures of ULF signals (Green *et al.*, 1993; Baransky *et al.*, 1995). In this work this approach has been applied to the ULF data from mid-latitude stations along 210° meridian, covering the range  $L = 2.9$ – $1.5$  in the Northern and the Southern Hemispheres.

## 2 Variations of ULF spectra along a meridian

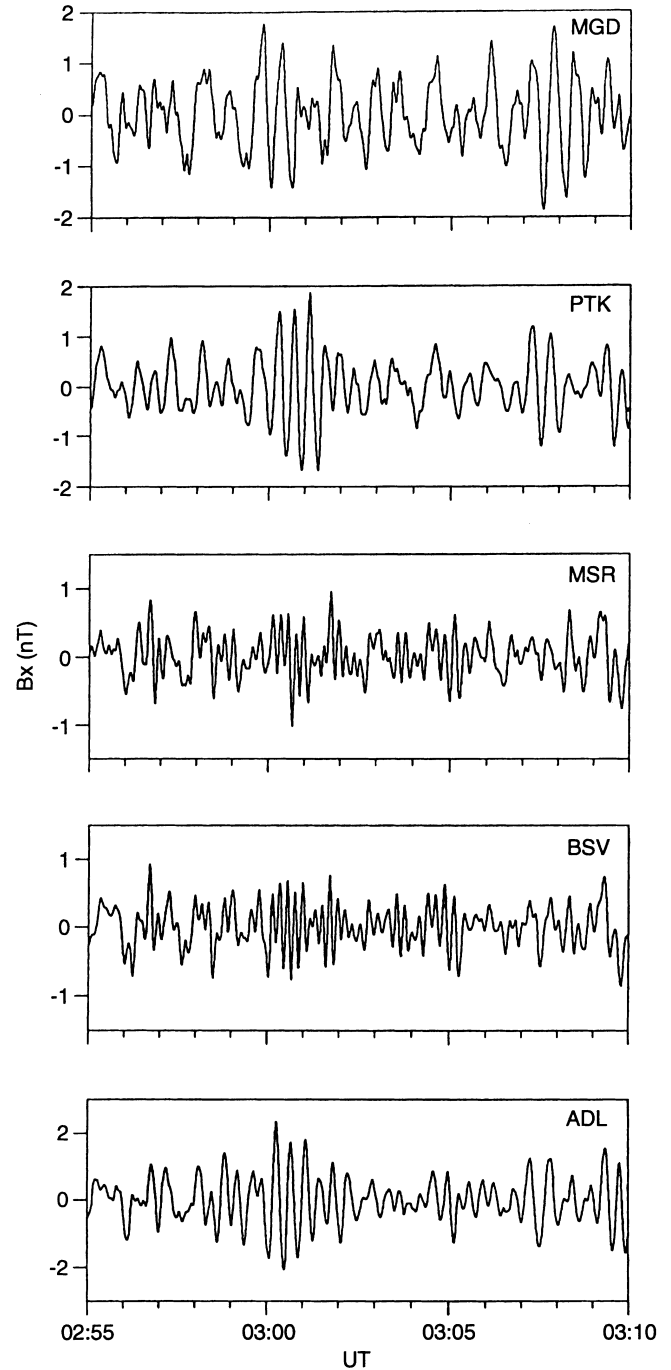
From the network elongated along the  $210^\circ$  meridian we have used the data of observations in September–October 1992 from the stations: Magadan (MGD,  $L = 2.85$ , geomagnetic longitude  $\Phi = 218.3^\circ$ ), Paratunka (PTK,  $L = 2.11$ ,  $\Phi = 225.6^\circ$ ), Moshiri (MSR,  $L = 1.60$ ,  $\Phi = 213.0^\circ$ ), in the Northern Hemisphere and Adelaide (ADL,  $L = 2.13$ ,  $\Phi = 213.3^\circ$ ), Birdsville (BSV,  $L = 1.57$ ,  $\Phi = 212.9^\circ$ ), in the Southern Hemisphere. The identical flux-gate magnetometers at each station enable us to record three-component magnetic variations between 0–0.5 Hz with a flat frequency response. Instrument sensitivity is about 0.1 nT and the time resolution is 1 s (Yumoto *et al.*, 1995b). For spectral and cross-spectral analysis the Blackmann-Tukey method has been used in the form described by Kurchashov *et al.* (1987).

The quasi-static variations, with durations of several minutes and more, are in-phase at all the stations of one hemisphere and their amplitudes decrease gradually towards the equator. In contrast with these quasi-static variations, the Pc3 ULF oscillations demonstrate a large variety of non-monotonic latitudinal distributions. A particular ULF response of the magnetosphere to an external source of wave energy with unknown spectra is determined, in our opinion, by the relationships between the spectral features of an external pulsation source and the local resonant frequencies. Depending on these relationships the seemingly different latitude-frequency distributions of Pc3 waves are observed. We now present two typical events.

### 2.1 A noisy source

The first event (1) 15.10.92, 02:58–03:08 UT is characterized by the obvious latitude dependence of spectral maximum frequency of the  $H$ -component and no evident spectral peaks in the  $D$ -component spectra. These series of Pc3 pulsations are observed under moderately disturbed geomagnetic conditions:  $K_p = 5^\circ$ ,  $D_{st} = -36$  nT. Figure 1 shows band-pass filtered 10–150 mHz magnetograms of the  $H$ -component at stations from Northern (MGD, PTK, MSR) and Southern (BSV, ADL) Hemispheres. Even a visual inspection of these magnetograms reveals the essential variations of amplitude and apparent period from station to station. The significant changes of a spectral content of the  $H$ -component between different latitudes for this time interval can be seen also in Fig. 2 (left panel).

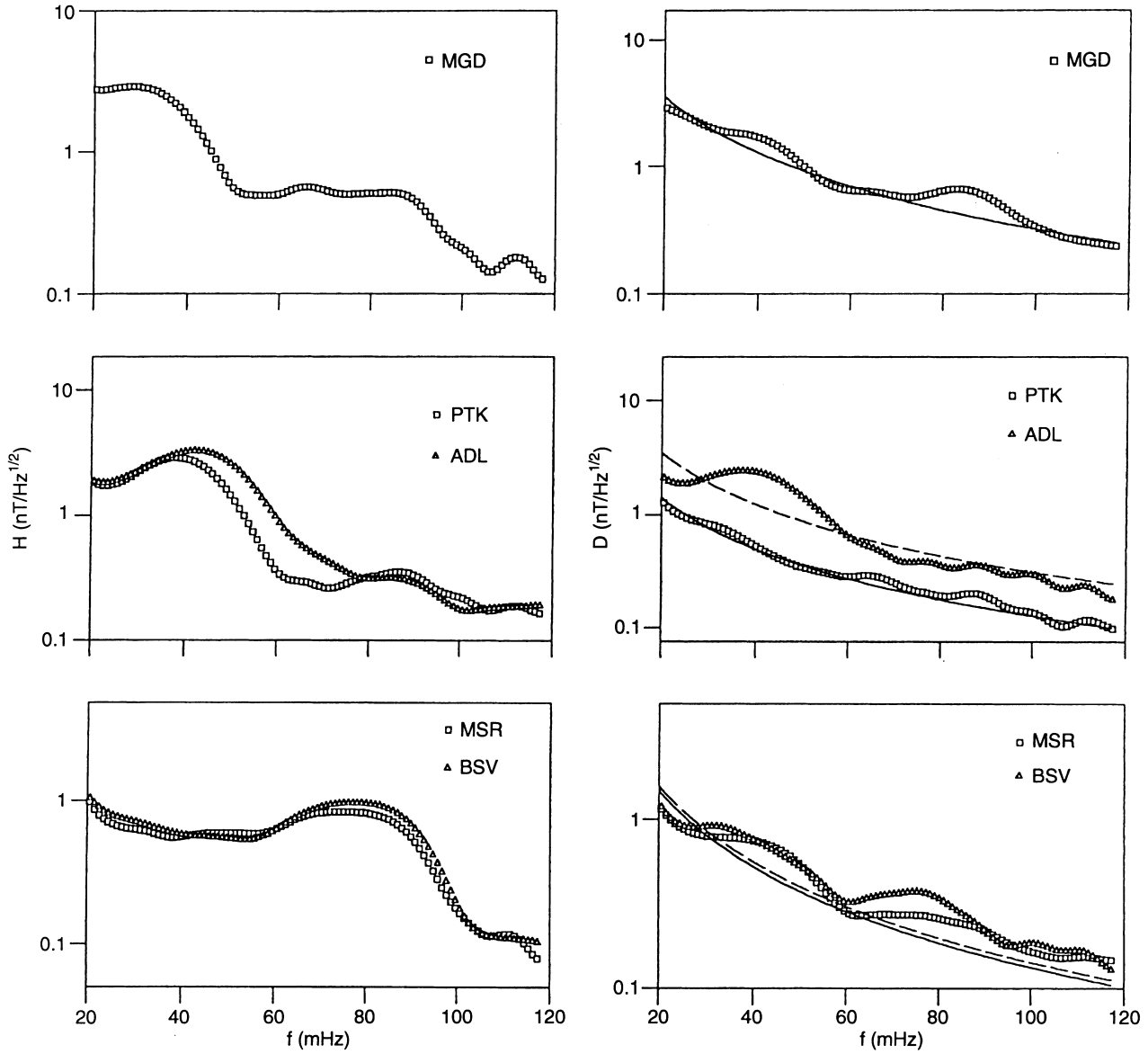
As a whole a spectral amplitude of the  $D$ -component decreases towards low latitudes (Fig. 2, right panels). The amplitudes at conjugate stations MSR and BSV ( $L \simeq 1.6$ ) are very close, some variation between PTK and ADL ( $L \simeq 2.1$ ) is probably related to the local time difference ( $\Delta\Phi \simeq 13^\circ$ ) or to the coast effect. The amplitude spectrum of the  $D$ -component gradually decreases with frequency of  $\sim f^{-\alpha}$ , where  $\alpha \simeq 1.5$  between 20–120 mHz. As the  $D$ -component should be only weakly influenced by resonant effects, it may



**Fig. 1.** Band-pass filtered in the range 10–150 mHz magnetograms of  $H$ -component of pulsations, recorded on October 15, 1992, 02:55–03:10 UT at mid-latitude stations of the  $210^\circ$  meridional network (event 1)

roughly characterize the spectral content of an ULF pulsation source.

In order to discriminate between a source frequency and local resonance frequencies and to isolate more clearly the fine spectral structure of the  $H$ -component, the background slope of each spectral curve has been compensated by the multiplication of spectral amplitudes by the factor  $f^\alpha$ . This procedure is similar to the pre-whitening technique or to the subtraction of general

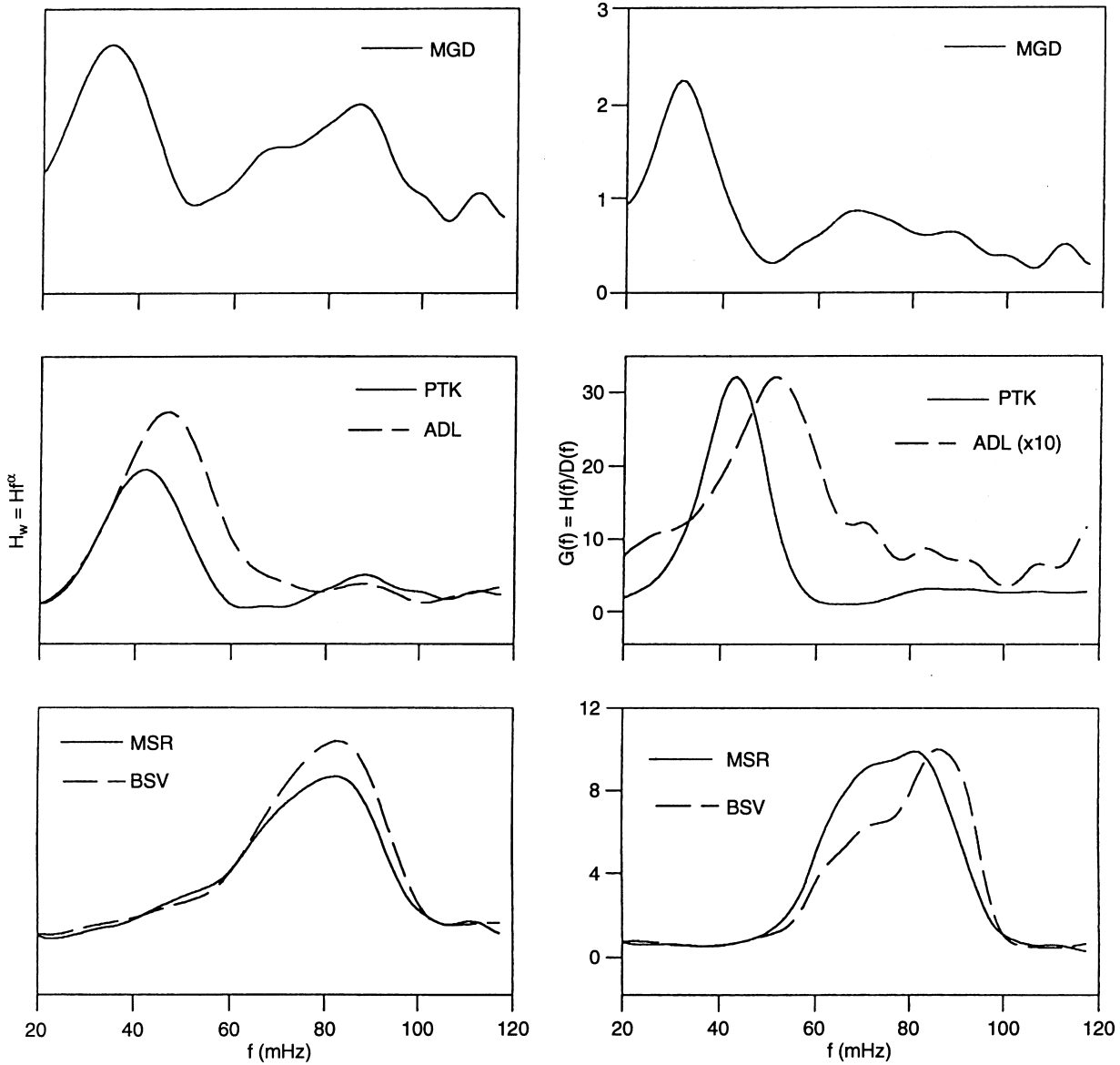


**Fig. 2.** Amplitude spectral densities for the interval 02:58–03:08 UT (event 1) of  $H$ -component (left panel) and of  $D$ -component (right panel). Spectral amplitudes are indicated by symbols, power best fit are shown by solid and dashed lines

spectral slopes, used by Vellante *et al.* (1993). After the elimination of the average spectral slope the fine structure of the  $H$ -component spectra exhibits specific pronounced spectral peaks (Fig. 3, left panel). Their frequencies systematically change with latitude: from 35 mHz at  $L = 2.85$  (MGD) to 45–50 mHz at  $L = 2.1$  (PTK/ADL), and further up to 85 mHz at  $L = 1.6$  (MSR/BSV). Presumably, these frequencies correspond to local eigen frequencies of field-line Alfvén oscillations. The additional peak at  $\sim 85$  mHz at MGD corresponds to a higher harmonic. The method of extracting resonant effects, which uses the  $H(f)/D(f)$  ratio (Baransky *et al.*, 1995; Vellante *et al.*, 1993), also stresses the same frequencies (Fig. 3, right panels). The additional argument in favor of the resonant nature of these spectral peaks is the fact that the signal coherency of  $H$ -component between conjugate stations PTK-ADL

and MSR-BSV increases in the relevant frequency bands (Fig. 4). At the same time the non-resonant  $D$ -component at all frequencies (dashed line in Fig. 4) is poorly correlated between stations. Low coherency between ULF signals in the same frequency range does not permit us to estimate reliably the latitudinal profile of phase characteristics.

Events of such type clearly demonstrate local resonance effects, whereas a central frequency of a probable source cannot be simply distinguished from ULF spectra at a single station. It may be speculated that local noisy contributions dominate over a band-limited source spectrum. However, cross-spectral analysis reveals an enhanced coherence between  $D$ -components of ULF signals recorded at distant stations at frequency  $\sim 40$  mHz (Fig. 5). According to the relationship between the expected upstream frequency and IMF



**Fig. 3.** Amplitude spectra of  $H$ -component (in arbitrary units) for the event 1 with corrected background slope ( $H_w(f) = H(f) \cdot f^\alpha$  (left panel), and the  $H(f)/D(f)$  spectral density ratio (right panel)

magnitude  $f \simeq 6.3B$  (Guglielmi, 1988) this frequency matches hour averaged (2–3 UT) IMF parameters:  $B = 6.3 \pm 4.1$  nT.

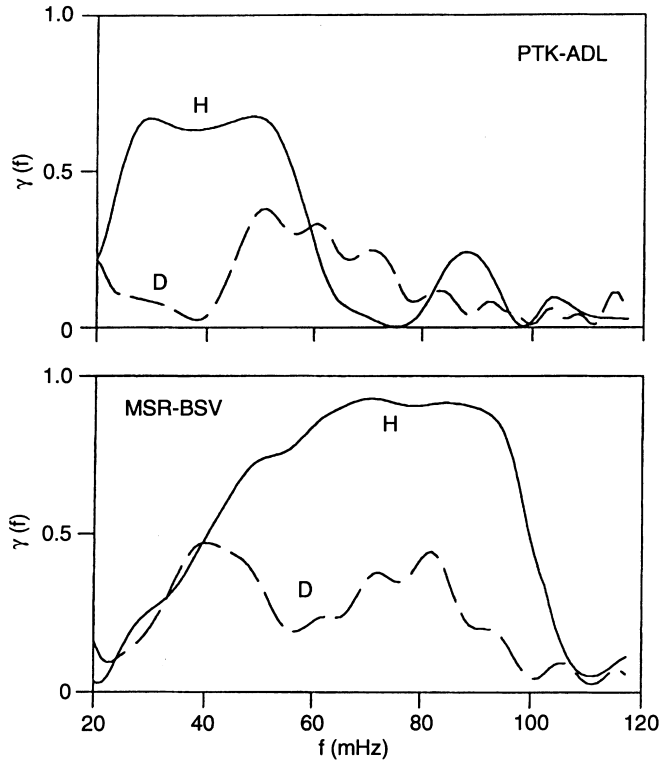
## 2.2 A source with a central frequency

The principal feature of another ULF event (2) 21:55–22:15 UT, 13.10.92 (Fig. 6) is the enhanced amplitude spectral density at a certain frequency throughout the network. This event occurs also in a moderately disturbed geomagnetic situation:  $K_p = 4^\circ$ ,  $D_{st} = -30$  nT.

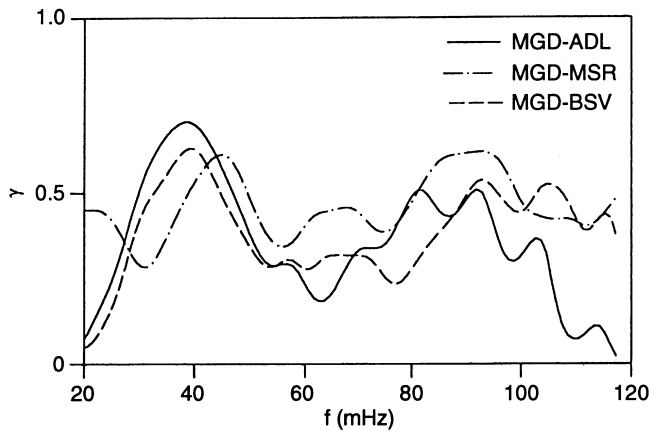
In this event the  $D$ -component spectra have a common maximum at  $\sim 60$  mHz, more or less evident at all stations (Fig. 7, right panel). The presence of a global forced response at this frequency also clearly reveals itself in the enhanced signal's coherency between

stations. In contrast to the previous event, for event 2 the signal's coherency between distant stations in the band 50–90 mHz is rather high,  $\gamma > 0.5$  (Fig. 8). The central frequency  $\sim 60$  mHz approximately agrees with the  $f \simeq 6.3B$  relationship for the frequency of upstream waves for hour-averaged (21–22 UT) IMF magnitude  $B = 10.7 \pm 6.8$  nT.

The spectral content of  $H$ -component for this event is more complicated compared with event 1, which is caused, probably, by a comparable mixture of forced and local resonant oscillations. The spectral maxima at the frequencies  $\sim 60$  mHz at  $L = 2.85$  (MGD), as well as  $\sim 35$  mHz and 80 mHz at  $L \approx 2.1$  (PTK-ADL) (Fig. 7, left panel), correspond to local resonant frequencies of fundamental Alfvén mode and its harmonics. This assumption is supported by the  $H(f)/D(f)$  ratio (Fig. 9). The phase relationships between signals at



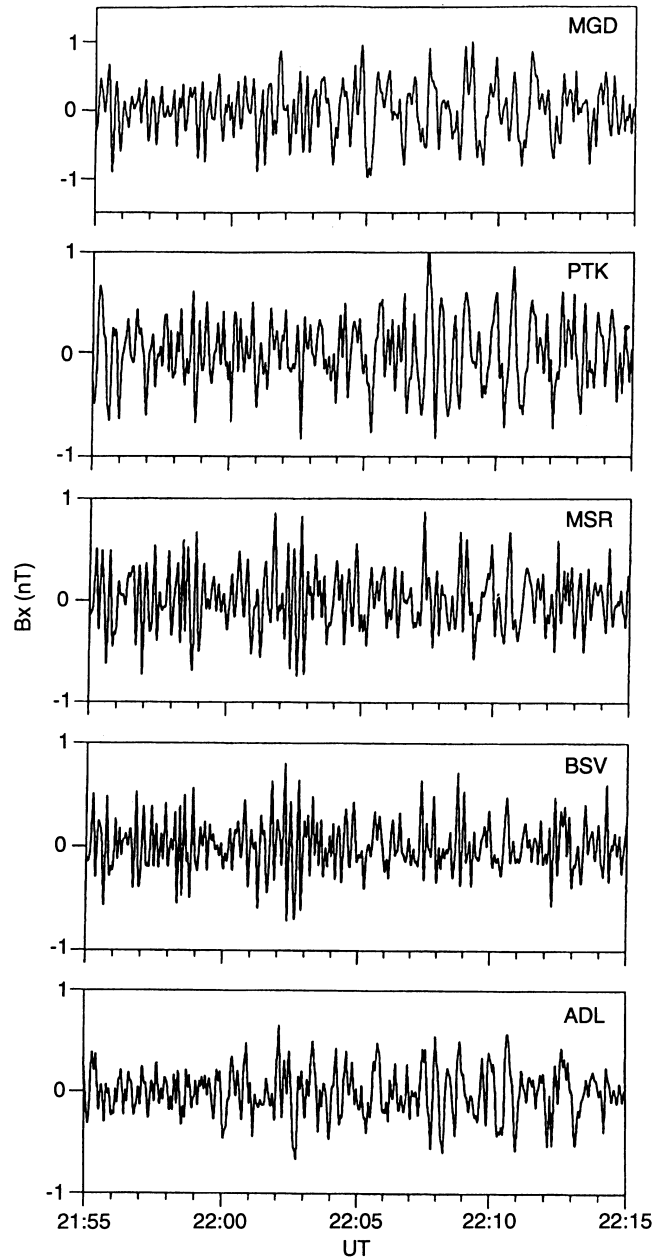
**Fig. 4.** Coherency coefficients  $\gamma(f)$  for the event 1 for  $H$  and  $D$  components between the conjugate stations PTK-ADL ( $L \approx 2.1$ ) and MSR-BSV ( $L \approx 1.6$ )



**Fig. 5.** Coherency coefficients  $\gamma(f)$  for the event 1 for  $D$  component between stations with different  $L$ -values

conjugate stations PTK-ADL (not shown) also confirm the existence of odd fundamental and even second harmonic: in the frequency bands of high coherency ( $\gamma > 0.5$ )  $H$ -components are in-phase at low (0–40 mHz) and out-of-phase at high (70–95 mHz) frequencies.

The local nature of resonant oscillations at  $L \approx 2.1$  results in low coherency between  $H$ -components at nearby stations PTK-MGD, PTK-MSR in the Northern Hemisphere and at ADL-BSV in the Southern Hemisphere near local resonant frequencies 35 and 80 mHz (Fig. 10). At the same time a high coherency between ULF signals at stations from different latitudes is observed at a source frequency  $\sim 65$  mHz (Fig. 10).



**Fig. 6.** Band-pass filtered in the range 10–150 mHz magnetograms of  $H$ -component of pulsations, recorded on October 13, 1992, 21:55–22:15 UT (event 2)

### 2.3 Amplitude gap in the latitude-period distribution

The spectral analysis of  $H$ -component reveals an interesting peculiarity of this class of ULF events. At the “common” frequency  $\sim 60$  mHz, which corresponds to a probable central frequency of an ULF source, a “gap” emerges at  $L \approx 2.1$  in the meridional distribution of power spectral density (Fig. 7, left panel). The local minimum in the meridional distribution of pulsation’s amplitudes in this frequency range has been observed at both conjugate stations PTK and ADL. Meanwhile, wide spectral maxima are observed at  $L = 2.85$  (MGD) and  $L \approx 1.6$  (MSR/BSV). Moreover, at this frequency at far magnetic shells (MGD-MSR and MGD-BSV) the

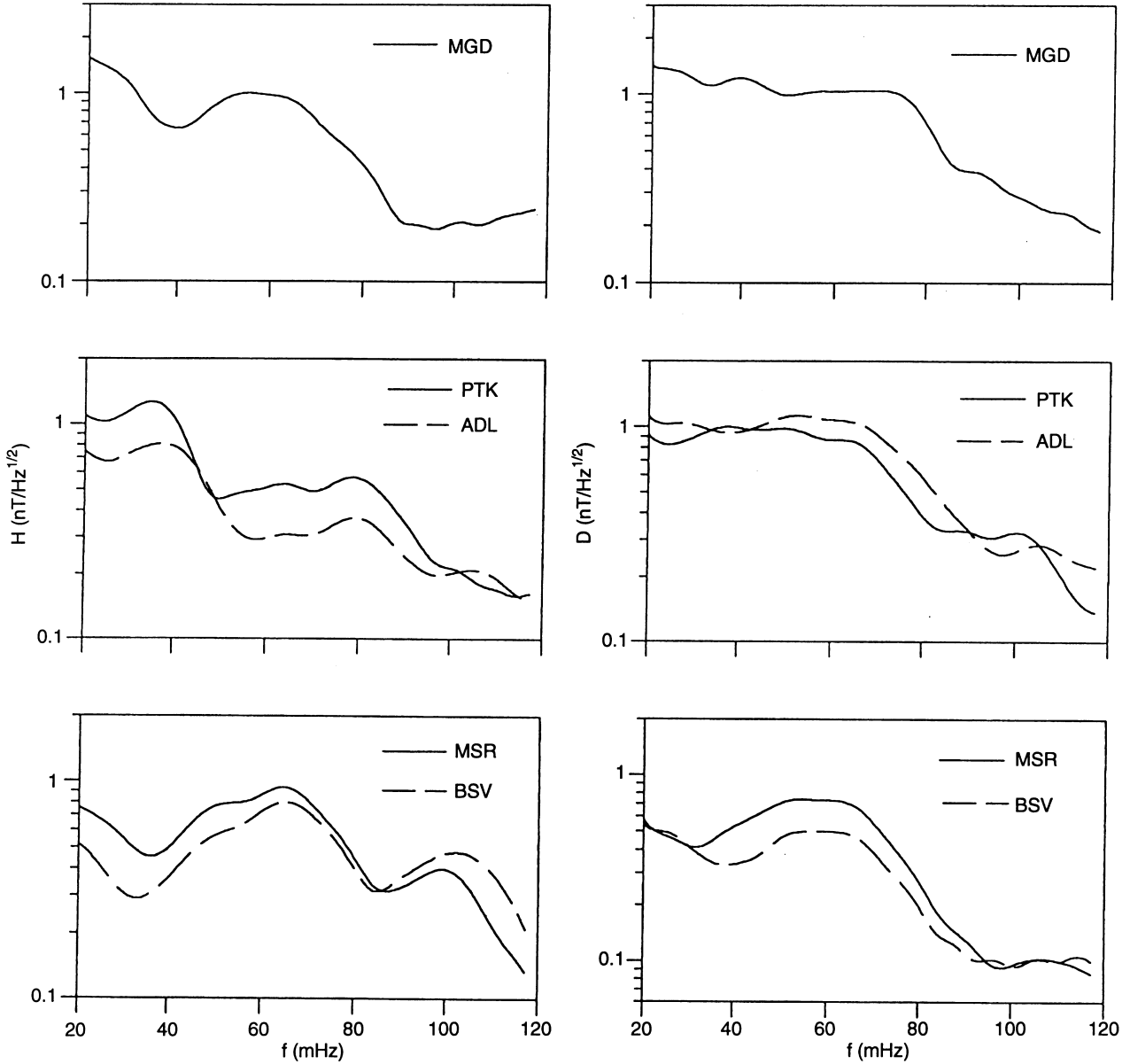


Fig. 7. Amplitude spectra of  $H$  (left) and  $D$  (right) components of pulsations for the event 2

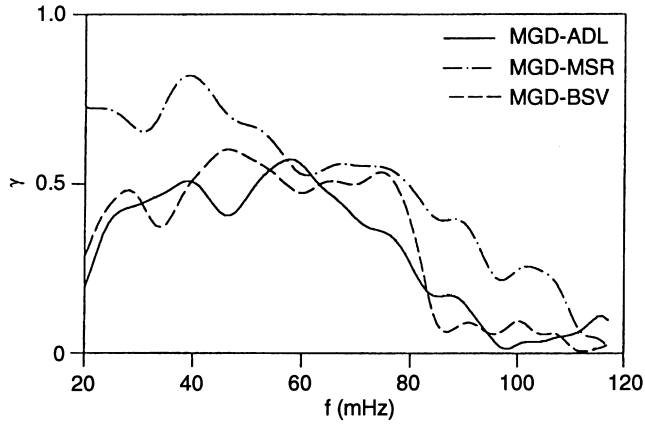
$H$ -components of signals in both hemispheres are even more coherent than the signals in closer shells (PTK-MSR, MGD-PTK, MGD-ADL and ADL-BSV) (Fig. 10). At both sides of a “gap”  $H$ -components of pulsations have no pronounced phase shift.

#### 2.4 Quasi-gradient method

The key moment in the reconstruction of a meridional distribution of resonant frequencies is related to the interpretation of spectra observed at  $L \approx 1.6$  (MSR/BSV). Two frequencies, which are about 60 mHz and 100 mHz, dominate the spectra of  $H$ -component (Fig. 7, bottom left plot). In principle, these peaks could be interpreted in two ways. On one hand, one may assume that 60 mHz is a fundamental resonant frequency and 100 mHz is its second harmonic. On the other had, one

may believe that the high-frequency peak corresponds to a local fundamental frequency, while low-frequency peak is a non-resonant response. To resolve this ambiguity the standard gradient method (Baransky *et al.*, 1995), which could indicate resonant frequencies, cannot be applied because of too large separations between stations. Nonetheless, some modification of the gradient method, in which the data of two nearly conjugated stations at  $L \approx 1.6$  (MSR and BSV) are used, can be applied. The mismatch in longitude between them is about  $0.1^\circ$  or  $\Delta L = 0.03$ . Plots from the top to the bottom in Fig. 11 demonstrates the results of the quasi-gradient analysis:

a. Ratio  $G(f) = H_L(f)/H_H(f)$  between spectral densities of  $H$ -components from the lower latitude station (BSV,  $L = 1.57$ ) and from the higher latitude station (MSR,  $L = 1.6$ );



**Fig. 8.** Coherency coefficients  $\gamma(f)$  for the event 2 for  $D$  component between stations with different  $L$ -values

- b. Phase difference  $\Delta\phi(f)$  ( $\Delta\phi < 0$  when the signal propagates towards higher  $L$ -values);
- c. Coherency coefficient  $\gamma(f)$ .

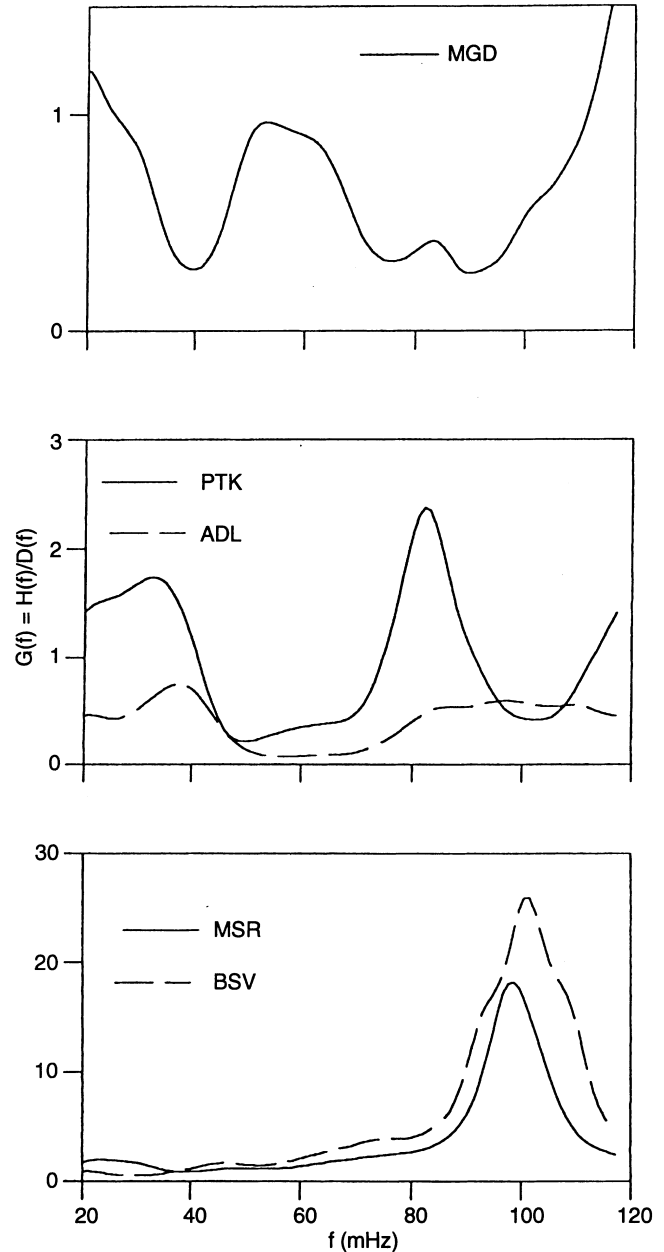
The ULF signals at conjugate stations are highly coherent,  $\gamma > 0.85$ , in wide frequency band 45–105 mHz (Fig. 11). The transition of  $G(f)$  over 1 and the minimum value of  $\Delta\phi(f)$ , both typical for any resonance region (Baransky *et al.*, 1995), can be seen only near the high-frequency peak. Hence, the amplitude and phase gradients definitely indicate the high frequency peak as a resonant one, while low-frequency spectral enhancement has a non-resonant nature. This conclusion has been supported by the examination of  $H(f)/D(f)$  ratio at each station, which also increased in the region of the high-frequency spectral peak (Fig. 9, bottom panel).

This interpretation can be verified also by the phase relationships between signals at conjugated stations: phase difference between  $H$ -components for two subsequent Alfvén harmonics should be opposite. However, in reality  $H$ -components at BSV and MSR are in-phase in the whole frequency range 40–100 mHz (Fig. 11).

### 2.5 Statistical distribution

Two examples shown are typical cases of possible frequency-latitude distributions. In one extreme case (type 2 events) spectral maxima are seen at the same frequency in both  $H$  and  $D$  components and the resonant effects are obscured. In contrast, in type 1 events, when a wide-band noisy component is prevailing, the local resonant responses are more evident.

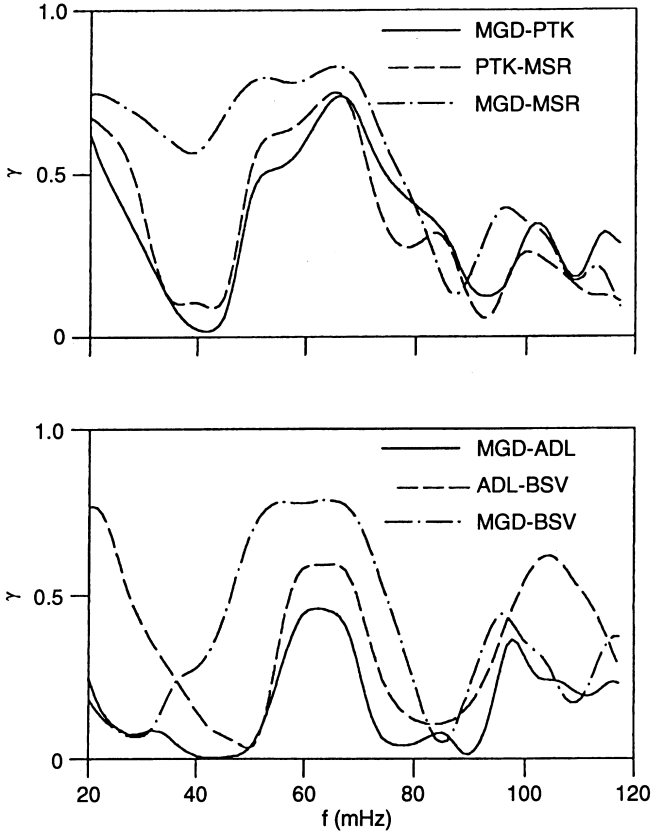
Commonly, in the spectral content of any Pc3 event both forced oscillations produced by an external source and local Alfvén distortions are present simultaneously. Discrimination between them is possible with the help of the polarization or the gradient analysis of a resonant component and the cross spectral analysis of a non-resonant component. Hereafter these approaches are verified on a statistical basis.



**Fig. 9.** The  $H(f)/D(f)$  spectral density ratio for event 2

In total we have analyzed about 60 h of Pc3 activity, recorded in time intervals 05–15 LT (20–06 UT). A current frequency of spectral maxima has been estimated in a moving 15-min window for all the intervals with Pc3 activity at each station. The frequency of a local peak has been determined when in a slope-corrected spectrum a height of a peak  $A_{\max}$  was above a certain threshold  $A_0$ , i.e.,  $A_{\max} > A_0$ , whereas the value of  $A_0$  was gradually increased with latitude. The resultant statistical dependence of the number of events  $N(f)$  with a spectral peak at frequency  $f$  is presented as histograms in Fig. 12a. The statistical distributions of the  $H$ -component emphasize the most probable frequency of spectral maxima at 40–50 mHz at all stations. The  $N(f)$  for the  $H/D$  ratio (Fig. 12b) demonstrates





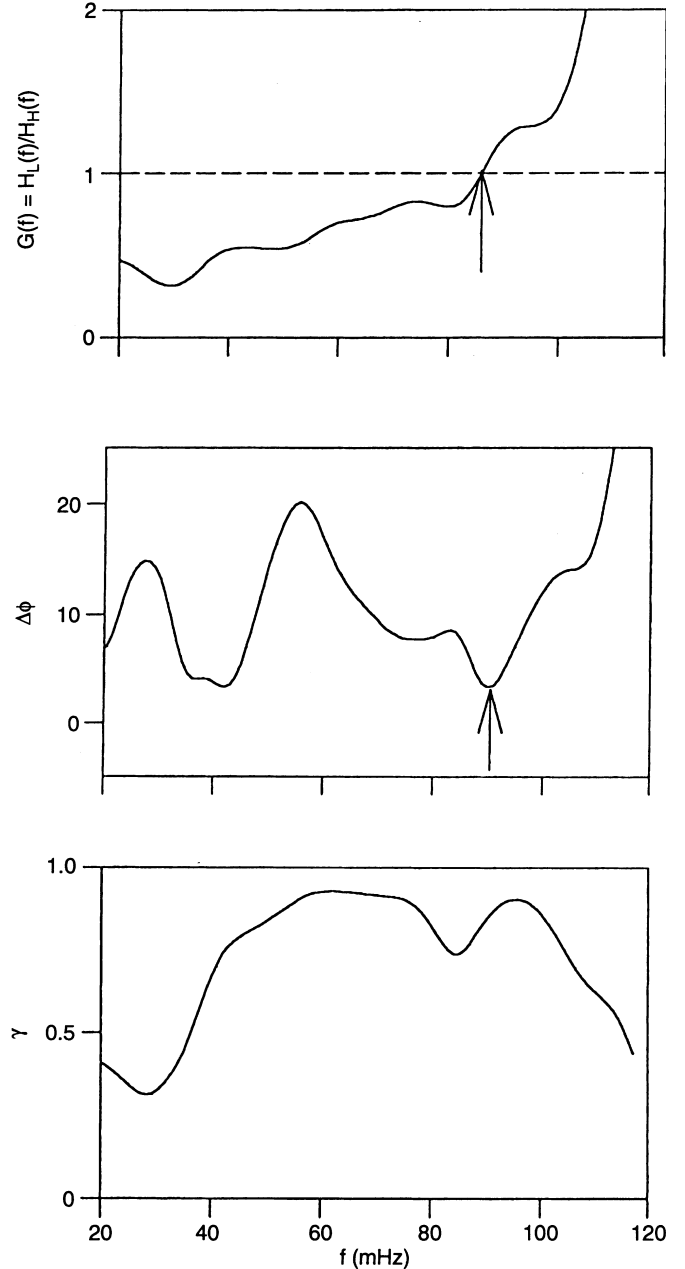
**Fig. 10.** Coherency coefficients  $\gamma(f)$  of  $H$ -components between different pairs of stations MGD, PTK, MSR for event 2. The *bottom panel* is the same for the stations MGD, ADL, and BSV

enhancements at some particular frequencies for each station. It is natural to relate them to the local frequencies of resonant shell oscillations. These frequencies are 40–50 mHz at  $L = 2.85$ , 40–50 mHz and 80–90 mHz at  $L \approx 2.1$  and 80–100 mHz at  $L \approx 1.6$ .

The solar wind and IMF parameters are available only for limited intervals of the analyzed period. No obvious distinctions between these parameters, such as  $B$ ,  $B_z$ ,  $V$ , etc., between ULF events have been seen. However, the solar wind velocity  $V \approx 712 \pm 32$  km/s during the type 1 event was somewhat higher than in event 2:  $V = 624 \pm 21$  km/s. In our opinion, the physical reason for the observed differences between those two types of events are related to small-scale features of the solar wind (turbulence level in the magnetosheath and its spectral form, intensity of upstream waves, etc.). All these features are not reflected in the 1-h averaged parameters from the IMF catalogue.

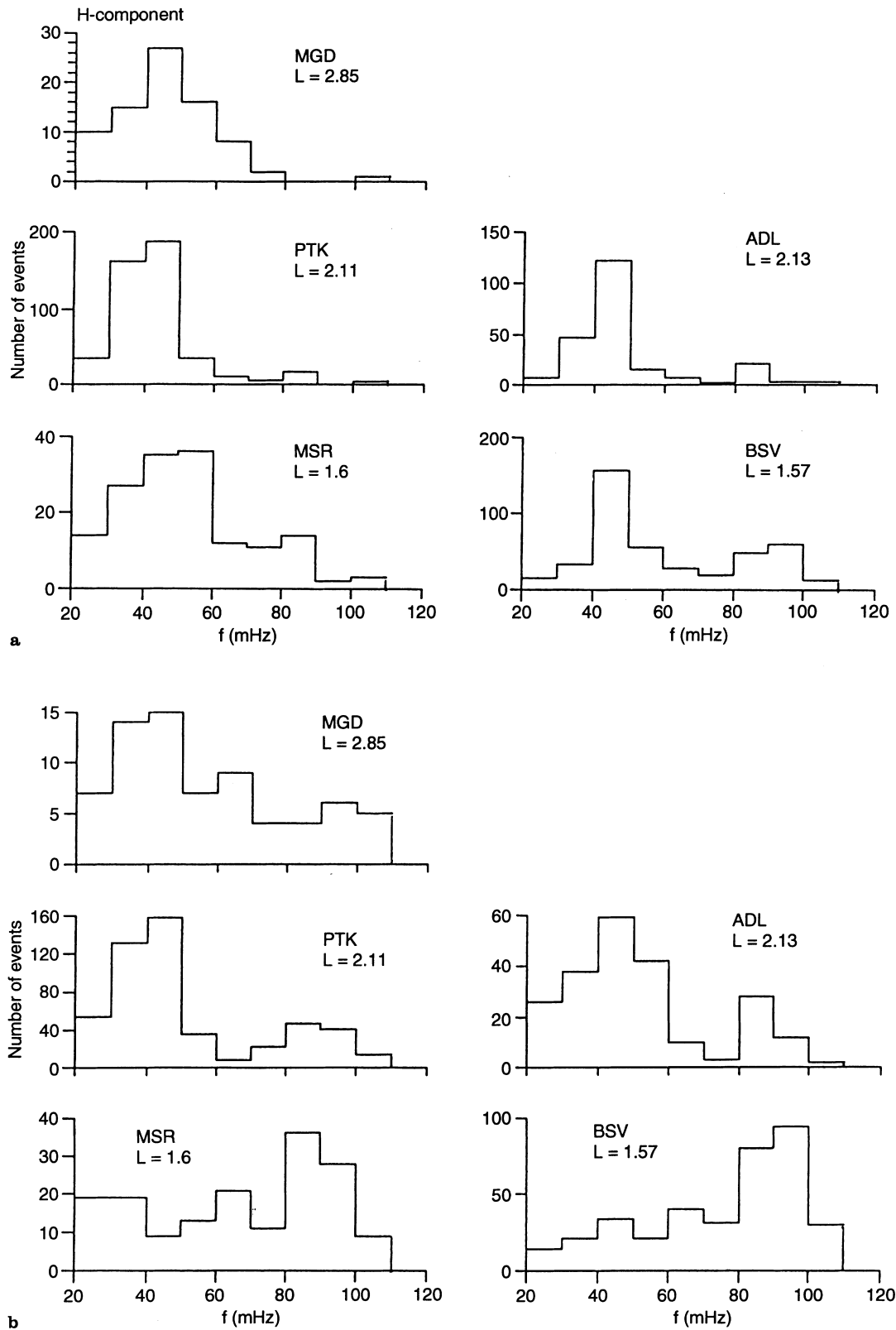
## 2.6 Dynamic hydromagnetic spectroscopy

In contrast to the problem of hydromagnetic diagnostics of magnetospheric plasma, for the study of correlative relationships between the IMF and ULF pulsations the monitoring of a central frequency of a source (which, most probably, is the dominant frequency of upstream waves) is more important. For that the preliminary



**Fig. 11.** The results of the quasi-gradient analysis of event 2 at near-conjugate stations MSR ( $H$ ) and BSV ( $L$ ) (from top to bottom): spectra ratio  $G(f) = H_L(f)/H_H(f)$ ; phase difference  $\Delta\phi(f)$  and coherency  $\gamma(f)$ . The resonant frequency of a field line between the stations is marked by an *arrow*

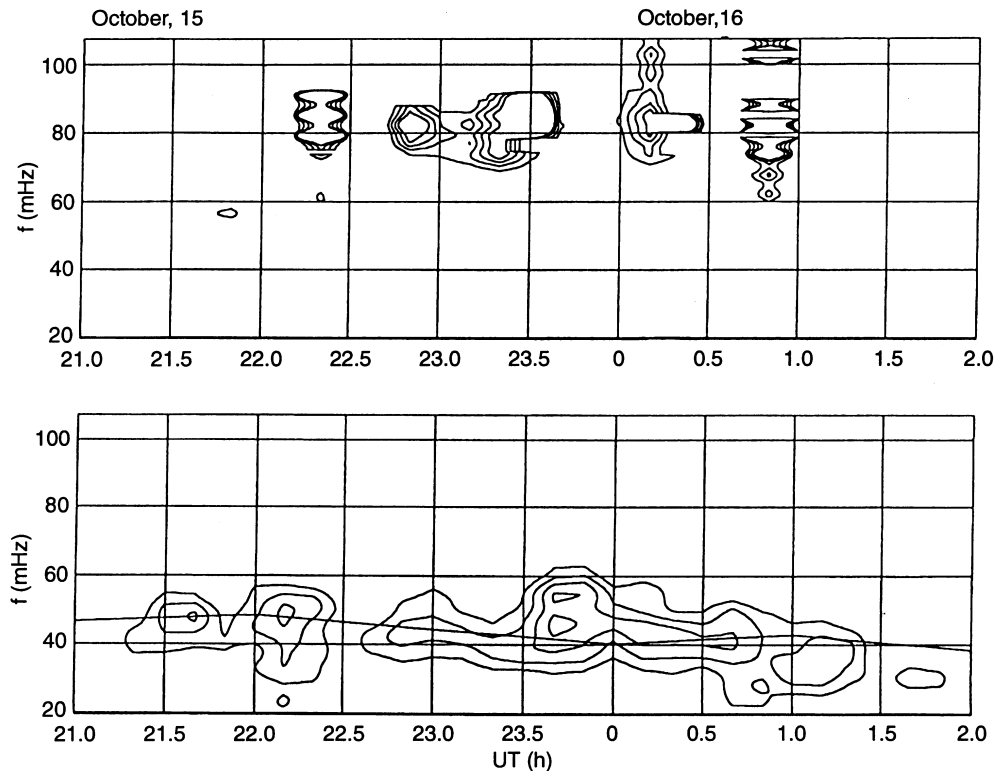
separation of different sources of ULF activity and the elimination of the resonant distortions of spectra are necessary. A rather simple technique may help to identify the nature of spectral peaks and to resolve different sources of the ULF pulsation's content. The principal possibility to monitor the temporal variations of both the local resonant frequency  $f_R$  and the source frequency  $f_o$  is illustrated in Fig. 13. The 5 h interval analyzed (onset on 21:00 UT on October 15, 1992;  $K_p = 5^\circ$ ,  $D_{st} = 35$  nT) is characterized by a relatively high pulsation activity during the whole interval. The upper plot demonstrates the contour of the  $H(f)/D(f)$



**Fig. 12a,b.** Histograms  $N(f)$  of number of intervals with maxima of  $H(f)$  (upper) and the  $H(f)/D(f)$  ratio (lower) at a frequency  $f$  for the Pc3 pulsations in September–October, 1992

ratio, estimated in a moving window, for the Pc3 series recorded at the station MSR. The lower plot presents, for the same time interval, the contours of the power

cross-spectrum of  $D$ -components between distant stations MGD and MSR. Comparison of these two plots show that from the same ULF series both  $f_R \approx 80$  mHz



**Fig. 13.** Variations of the resonant frequency  $f_R$  at  $L = 1.6$  (upper) and the expected source frequency  $f_0$  (bottom) of Pc3 pulsations recorded on October 15–16, 1992. The solid line in the lower panel shows the frequency estimated with the  $f = 6.3 B$  relationship

(determined as the frequency of maxima of  $H(f)/D(f)$  ratio) and  $f_0 \approx 40$ –50 mHz (determined as the frequency of amplitude cross-spectra maxima) can be extracted and monitored with good time resolution.

The probable upstream wave frequency estimated from the  $f = 6.3B$  relationship varies between 48–40 mHz and within the accuracy of the proposed technique coincides with the frequencies of the cross-spectral maxima in Fig. 13. Successful attempts to separate these frequencies and to study their variations during the solar cycle have been undertaken recently by Vellante *et al.* (1995). It might be worth re-examining the numerous existing results on ULF-IMF correlations with a more correct preliminary analysis of ULF pulsation's spectra.

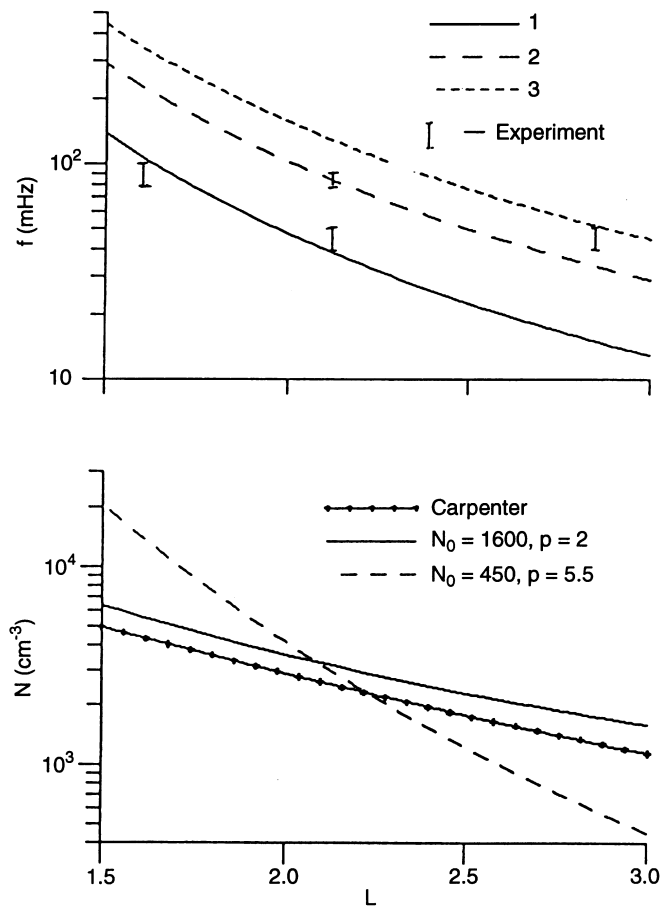
### 3 Theoretical interpretation

Specific features of the magnetosphere as an oscillatory system are caused by the presence in the eigen mode spectrum of the frequency bands with continuous spectra corresponding to the Alfvén oscillations. An initial disturbance with frequency  $f_0$  generates two way processes in such systems: forced oscillation with a frequency  $f_0$  and transient oscillations with a space-varying frequency  $f_R(X)$ . The variety of the possible wave regimes is due to the superposition of forced oscillations and transient oscillations, having an inhomogeneous spatial distribution of amplitudes and damping rates (Allan *et al.*, 1986). Meridional distribution of a resultant oscillation at a given frequency  $f_0$  demonstrates rapid enhancement of amplitude and phase jump

( $\sim \pi$ ) in the Alfvén resonance regions where  $f_0 \approx f_R(L)$ . Wave field structure near the resonant shell is described by the well-known steady-state solution from the field-line resonance theory (Southwood, 1974). The observed amplitude-phase distribution of Pc3 along a meridian should be determined mainly by the relationships between source frequency  $f_0$  and local resonant frequencies of stations.

#### 3.1 Hydromagnetic diagnostics of magnetospheric plasma density

The statistically determined values of local resonant frequencies  $f_R(L)$  from ground-based data (Fig. 12b) have been compared with the eigen frequencies of Alfvén oscillations in the inner plasmasphere. For that the numerical model of an Alfvén resonator, which is based on the integration of local differential equation along a field line with boundary condition in the “thin ionospheric approximation”, was used. This model can be applied till  $L \approx 1.4$ , while at lower latitudes due to the mass loading effect of ionospheric ions the “thin ionosphere approximation” becomes invalid (Yumoto *et al.*, 1995a; Pilipenko *et al.*, 1997). The plasma distribution along a field line is characterized by the parameter  $p$ ,  $N(\theta) = N_{eq}(\cos \theta)^{-2p}$ , where  $\theta$  is latitude. The fit between the frequencies of fundamental mode and its harmonics was obtained for the value  $p = 3.0$ . The empirical whistler-ISEE model of Carpenter and Anderson (1992), being extrapolated into the region  $L < 2.2$ , was used for the equatorial plasma density. The calculated values of frequencies of the first three

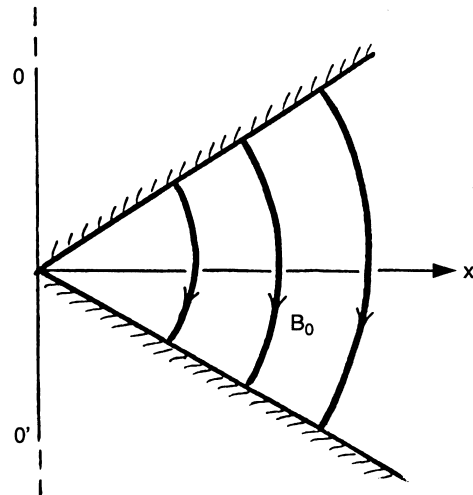


**Fig. 14.** Radial profile of latitude-dependent resonant frequencies approximating the experimental data (*dashes*) from the meridional network. *Solid line* corresponds to calculated frequencies of the fundamental mode, *dashed lines* – of 2-nd and 3-d harmonics

harmonics of Alfvén oscillations along with the experimental values are plotted in Fig. 14. The 40–50 mHz oscillations at  $L = 2.85$  may be interpreted as the third harmonic, 40–50 and 80–90 mHz at  $L \approx 2.1$ , as the fundamental mode and the second harmonic, and 80–100 mHz at  $L \approx 1.6$ , as the fundamental mode of Alfvén oscillations.

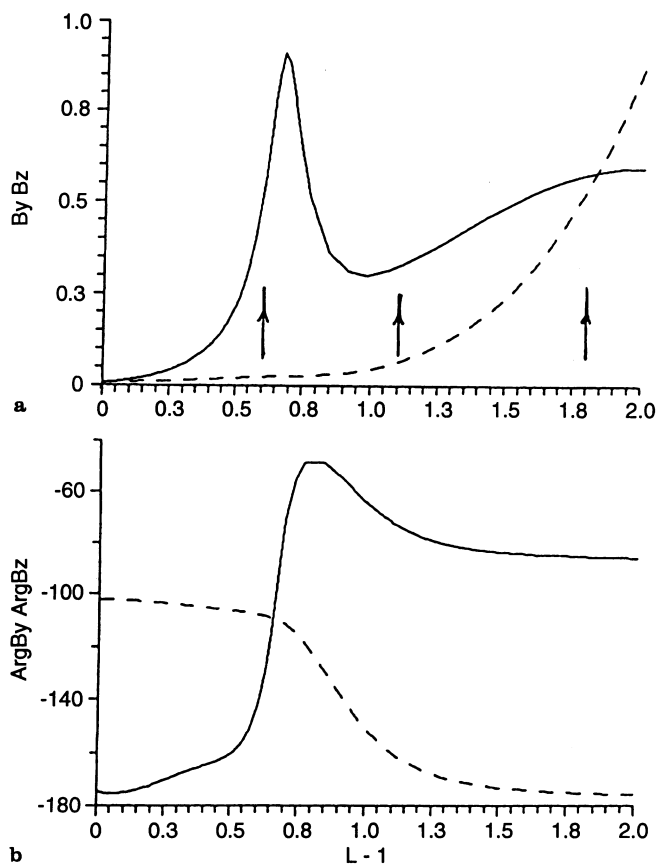
### 3.2 Modeling of the gap in the meridional ULF structure

In the second type of ULF events an effect of the local  $H$ -component amplitude gap, forming at  $L \approx 2.1$ , has been exhibited at both PTK and ADL. The effect of local decrease of the  $H$ -component amplitude at  $L \approx 2.1$  cannot be explained by the local geoelectrical conditions (e.g., coast effect), because it was displayed at both conjugate stations. The emergence of the amplitude gap cannot be explained either by the presence near  $L \approx 2.1$  of a cavity-mode node, because the necessary out-of-phase relationship between signals from both sides of a node does not hold. Next we consider the most probable, in our opinion, possibility of the interpretation of this effect.



**Fig. 15.** A schematic plot of the geometry of the inner plasmasphere, used in the model calculation of ULF meridional structure

For modeling of spatial structure of ULF pulsations in the inner magnetosphere we numerically calculated the radial profiles of components of MHD wave excited by an external harmonic source. We used the magnetospheric model, whose meridional cross-section is a wedge, schematically shown in Fig. 15. The whole structure is formed by the azimuthal rotation of this cross section around the  $00'$  axis. Though this model is mathematically more complicated (variables are not separable) than the well-known “box-field” model (Southwood, 1974) or the “cylindrical wedge” model (Allan *et al.*, 1986), it allows us to consider the decrease of the effective azimuthal wave number  $k_y = m/LR_E$  and the inhomogeneity scale in the inner plasmasphere. Figure 16 displays the results of calculations of amplitudes (Fig. 16a) and phases (Fig. 16b) of the field aligned  $B_z$  (dashed line) and the azimuthal  $B_y$  (solid line, corresponding to the resonant  $H$ -component at the Earth’s surface) magnetic components. The following wave parameters have been adopted: azimuthal wave number  $m = 4$ , source frequency  $f_0 = 50$  mHz. The numerical results prove that a gap in a meridional profile of ULF wave amplitude can be formed on the source side of a resonant region. The phase jump by  $\sim \pi/2$  of  $B_z$ -component (Fig. 16b) can be interpreted as the superposition in the magnetosphere of an “incident” wave from a source and a wave “reflected” with phase shift  $\sim \pi/2$  from a resonant magnetic shell. In the wave structure which is formed in front of a resonant maximum the local decrease of amplitude and the partial phase shift compensation take place. Thus, a situation is possible like that shown in Fig. 16, when a comparison of ULF signals at several widely separated stations (marked by arrows) would display the gap at the mid-station and only a small phase shift ( $\sim 60^\circ$ ) between the stations at both sides of a resonant field line. At  $210^\circ$  MM network the non-monotonic amplitude profile emerges due to the resonant amplification of pulsations somewhere between  $L = 1.6$  and  $L = 2.1$ .



**Fig. 16a,b.** Numerically calculated radial distribution of the amplitudes  $B_y$ ,  $B_z$  (upper plots) and phases  $\text{Arg}(B_y)$ ,  $\text{Arg}(B_z)$  (bottom plots) of the components of ULF wave structure in the magnetosphere. Wave parameters are  $m = 4$ ,  $f = 50$  mHz

## Discussion and conclusion

Analysis of the data of mid-latitude stations from the 210° MM network showed that spectral content of ULF pulsations at various latitudes may vary considerably from one station to another even at separations of  $\Delta\Phi \simeq 7\text{--}8^\circ$  ( $\Delta L \simeq 0.5$ ). The form of the observed spectra are mainly determined by features of the pulsation's source spectrum and by local response of the magnetospheric resonator. The identification of nature of spectral peaks, which was named the hydromagnetic spectroscopy, cannot be performed by the analysis of spectra of one component only, at some particular station. In an optimal way, this problem can be resolved by the combination of stations with small ( $\sim 100\text{--}200$  km) and large ( $\sim 10^3$  km) baselines. For the meridional network 210° MM the unambiguous isolation of resonant frequencies at  $L \simeq 1.6$  was performed with the help of the quasi-gradient method, which uses the data of nearly conjugate stations. The results of the suggested method are in accordance with the results of the polarization method, based on the asymmetry of the spectra of two horizontal components. Using the experimentally measured set of resonant frequencies the magnetospheric plasma distribution has been restored both in a radial direction and along a field line. It

is essential that the ULF pulsation recordings prove to be a reliable method of ground-based diagnostics of the magnetospheric plasma density at low latitudes also, where the standard whistler diagnostics becomes ineffective.

The numerical modeling of MHD wave structure proved that a gap in a meridional profile of ULF wave amplitude can be formed on the source side of a resonant region in the inner magnetosphere. In the gap, the amplitude decreases and the partial compensation of the resonant phase jump takes place. During observations at widely separated stations along a meridian (e.g., at 210° MM profile) this effect may obscure a phase jump at a resonant shell.

In some cases (type 1 events) the level of ULF disturbances, transported into the inner magnetosphere by large-scale compressional modes, is below the magnetospheric noise. The appearance of quasi-sinusoidal signals at the ground is caused mainly by magnetospheric resonances. However, a frequency band of a source can be found by the coherency analysis of ULF signals from meridionally separated stations.

In a prevailing number of events (type 2) the source spectrum is identified as an enhanced spectral power density at certain frequency. This frequency might be related to the frequency of unstable upstream waves (Yumoto, 1985) or to the selective penetration of solar wind energy into the magnetosphere (Pilipenko, 1990). Simple methods of hydromagnetic spectroscopy enable us to monitor simultaneously from ULF data both the magnitude of IMF and plasma density in the magnetosphere.

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